Globe Valves Actuators

MVE5xx

Model	Force [N]	Power supply	Description
MVE506	600	24Vac/dc	long yoke, modulating/ floating control
MVE510	1000	24Vac/dc	long yoke, modulating/ floating control
MVE515	1500	24Vac/dc	long yoke, modulating/ floating control
MVE506S	600	24Vac/dc	short yoke, modulating/ floating control
MVE510S	1000	24Vac/dc	short yoke, modulating/ floating control
MVE515S	1500	24Vac/dc	short yoke, modulating/ floating control





APPLICATION AND USE

MVE is a flexible electro mechanical actuator for the control of two and three-way globe valves in:

- heating and cooling systems;
- Air Handling Units;
- district heating plants;
- industrial temperature control systems.

The actuator can be controlled either by a proportional (modulating) signal or by an increase/decrease (Floating) signal.

It is easy to mount and connect the actuator. Direct mounting is possible to any CONTROLLI flanged valve. Linkage kits are available for CONTROLLI threaded valves as well as for valves of other manufacturers (table p. 3). The actuator has a fine resolution (500 steps on the full stroke range) for exacting fluid control and it is able to self-calibrate on a different stroke without the need of any user action (this function is DIP switch selectable on the field).

MVE has intelligent behaviour and alarm functionality in case of unexpected operation, feedback of alarms to the user is provided by LEDs (GREEN and RED) on the control board.

N.B.: Do not use the actuator if not coupled with its relating valve.

OPERATION

The actuator translates the control signal (modulating or 3 point floating) from the controller into a valve position. A modern brushless DC motor in the actuator drive a gear train and a worm gear – screw jack mechanism convert the motor revolutions into accurate and repeatable linear movements.

Control Signal

MVE can be controlled by one of 2 main control types:

- 3 point floating ;
- Modulating (or proportional) signal with filed selectable range (e.g., 0-10Vdc, 2-10Vdc, 0-5/2-6Vdc, 5-10/6-10Vdc and 4-20mA).

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CONTROLLI



Manual Override

There is a manual operation handle on the actuator. When it is lowered (manual override ON), the power supply to the motor power stage circuitry is cut and the motor stops. The actuator can be operated manually and the valve positioned accordingly.

The manual override lever stays in position until it is raised again, then board and motor will be powered again. At the end of this operation the actuator moves to initial position (on the basis of DIP n. 1 setting) then it follows the control signal. When the manual override is engaged the GREEN and the RED LED are ON.

Manual operation handle can also be used to modify any DIP switch setting or as re-set function after any alarm occurrence.

The actuator is supplied with the manual override lowered (ON). It is not necessary to remove power supply to modify DIP switches setting.

Position Feedback

The actuator utilizes a 2-10Vdc position feedback (look at DIP n. 1 setting).

Calibration

The actuator has both auto and manual stroke calibration, DIP n. 7. In factory delivery the auto stroke calibration is enabled – manual calibration is not necessary unless maintenance is required on the valve or certain alarm functions are desired.

End Point Auxiliary Switches (with accessory DMVE)

End point switches change over when the valve is fully open or closed. They are free contacts with 24V AC/DC, 4A max voltage on terminals. End point switches can be utilized to indicate valve stroke end positions and for relay control of additional plant equipment. When the actuators are controlled individually or in sequence, it is possible to use the end switches to toggle when the valve is fully open or fully closed. The auxiliary switch position according to control signal (Y) is shown in the picture below.

Control signal (Y)	Relay KC1	Relay KC2
0-0,5Vdc	KC1 to K2	KC2 to K3
0,5-9,5Vdc	KC1 to K1	KC2 to K3
9,5-10Vdc	KC1 to K1	KC2 to K4



Diagnostic

The actuator is provided with a self diagnostic algorithm able to detect faulty conditions:

- stroke calibration out of range 5-60mm;
- unexpected stall condition (e.g. valve stuck or extra stroke due to actuator link loose);
- voltage supply out of range.

These faulty conditions are signalled through the GREEN and RED LED on the electronic board blinking accordingly (see Diagnostic – Alarm Function Table).

TECHNICAL FEATURES

	MVE506 MVE506S	MVE510 MVE510S	MVE515 MVE515S
Supply voltage L1 Ln		24Vac ±20% 50-6	
Power consumption (running)	13VA / 6W	30Vdc (Referend) 18VA / 8W	21VA / 11W
Power consumption (holding)	11VA / 5W	11VA / 5W	13VA/7W
Running time			
Modulating 5-15mm		15s	
Modulating 15-25mm		20s	
Modulating 25-60mm		30s	
Floating		60s	
Transformer Size [VA]	20	30	50
Stroke	-	mited to 30mm f	
Force [N]	600	1000	1500
Duty cycle		ax 50%/60 minute	
Analogue input Y M	voltage 0-10Vdc 0-10Vdc, 2-10V	c - impedance > dc, 0-5/2-6Vdc, 3 Ω (range 4-20m)	• 100k Ω (range: 5-10/6-10Vdc)
Digital inputs Y1 Y2		L1 or Ln when po Ln only when po	
Output V+	volto	age 16Vdc ± 0,5V	/dc
1	r	max load 25mA,	
Output U	voltage 2-10Vdc (0-100%) max load 2mA		
Number of cycles of manual action			
Number of cycles of automatic action	100.000		
Type of action	type 1		
Type of movement	linear		
Room temperature	operation -	operation -10T50°C; storage -20T50°C	
Room Humidity	max 90% R.H.		
Protection degree	Nema 2 (*) / IP54 (**)		
Insulation class			
Printed Circuit Board	FR4 (material) PLC (Performance Level Categories) = 3 PTI (Proof Tracking Index) = 175 - 249V CTI (Comparative Tracking Index) = PTI Pollution Degree = 2		175 - 249V ndex) = PTI
Standard	Emission/Immunity EMC 2004/108/CE accordin to EN 61326-1:2006 standard		
Standard(s) for safety	UL 60730-1A Part 1: General Requirements UL 60730-2-14 Part 2: Particular Requirements Electric Actuators CAN/CSA-E60730-1:02 Part 1: General Requirements with Amendment 1		equirements for 1: General
Material	housing: aluminium - cover: ABS plastic		
Colour	aluminium / white		
Weight [kg]	1,7 (MVE5xx); 1,6 (MVE5xxS)		
Dimensions [mm]	refer to the picture on the page 7		
Date code		yy/ww	



*To guarantee "Nema Type 2" protection:

- use flexible metal conduit (not supplied);
- Push the listed conduit fitting device (PG13,5 not supplied) over the actuator's cable to butt against the enclosure. Screw in conduit connector. Jacket the actuators input wiring with listed flexible conduit. Properly terminate the conduit in a suitable junction box.

**To guarantee IP54 protection

Insert the actuator cable in the PG13,5 cable gland (not supplied)

ASSEMBLING

The actuator can be mounted with any orientation but never up-side down. When the fluid temperature exceed 120°C the actuator shall be mounted leaning 45°.



To mount the actuator on to a valve, position the valve stem to the bottom of its travel, slide the actuator onto the valve neck, adjusting with the manual override the screw jack position so the square nut on the valve spindle fits into the groove on the cross bar. Then slide the brace into the groove on the valve neck and secure the nuts.



See mounting instructions for full details (MVE_DIM223).

MAINTENANCE

The actuator is free of maintenance.

ACCESSORIES

DMVE	End point auxiliary switches (electrical rate 24V AC/DC, 4A max)
248	Yoke heater (suggested when the fluid temperature is be- low 0°C)
GMVE	Thermal insulation for MVE actuators
GMVE.S	Thermal insulation for MVE.S actuators

Linkage	MVE	MVES		
Current Controlli valves (except for 2TGB.F/3TGB.F PN16)	(not required)	/		
2TGB.F/3TGB.F PN16	/	(not required)		
Controlli valves with threaded M40 connections (except for VSB/VMB/VSBF/VMBF PN16)	AG51	/		
VSB/VMB/ VSBF/VMBF PN16	AG52	AG63		
Other manufacturers				
Landis *	AG70-10 AG70-14	/		
Danfoss (VR/VF (S) models)	AG60-07	/		
TAC DN15-V298	AG 60-08	/		
TAC DN15-V2XX/V3XX	AG 60-09	/		
Honeywell**	AG 60-10	/		
Airtek	AG 60-11/ AG60-12	/		
Johnson Controls code VB7816- 2111	AG 66	/		
Johnson Controls code BM-3018- 3300	AG 67	/		
Tac Venta	(not required)	/		
 (/) this model can not be assembled (*) AG70-10 for valves having stem Ø 10mm AG70-14 for valves having stem Ø 14mm 				
(**) valid for the following models: M6: V176A. B, V538C 1/4": V5011A				

ELECTRIC CONNECTIONS

Remove the cover screw with a screwdriver and then remove the cover as shown in the picture beside.

The actuator is equipped with a 8 poles removable terminal block; the each pole of the plug is clearly marked and the same label are reported on the electronic board. Before powering up the actuator make sure the plug is properly connected to the board and the label on the plugs and on the board match.



Use PG13,5 cable gland (not supplied).





Label	Description	Function	Cable type	Max wire length	
Ll	24Vac/dc	Power	AWG 16 (min 1mm² - max	75m	
Ln	0V	supply	1,5mm²)	7511	
Y	0-10Vdc	Modulating control	AWG 20 (min 0,5mm² - max	200m	
м	0V (common)	input	1,5mm²)	200111	
Y١	Open	Floating	AWG 20 (min 0.5mm² - max	200m	
Y2	Close	input	0,5mm ²)	20011	
V+	16Vdc	Voltage output max	AWG 20 (min	200m	
м	0V (common)	25mA	0,5mm² - max 1,5mm²)	20011	
U	2-10Vdc	Feedback output	AWG 20 (min 0,5mm² - max	200m	
м	0V (common)	signal	0,5mm ² - max 1,5mm ²)	20011	

Note: To avoid damages to electronic components caused by the PCB bending, do not press too much while fixing the terminal block.

Matching between	MVE terminal block	and others Controlli
actuators		

1	2	3	4	5
L1	L2	М	V+	Y
G	G0	MX	G1	X1
L1	LN	м	V+	Y

SH500

MVB5-MVL5-MDL5

MVF-MVH5-MVL5-F

MVE









N.B.: M and Ln signals are internally connected.

(*) MVE contain a single half-wave rectifier power supply. They must not be powered with transformers that are used to power other devices using not isolated double half-wave rectifier power supply.



Set the DIP switches according to the tables here below. Power down and power up again the actuator or act on the manual override to be sure that settings will be recognized.



DIP switch	OFF	ON
1	U = 2V U = feedback $U = 10V$	U=feedback
2	Modulating Control (MOD) (Input between Y [+] and M [-])	3 point floating (INC) (Y1 open-extend , Y2 close-retract connected L1 or Ln if powered in Vac; if powered in Vdc connected necessarily to Ln)
3	-	Selection of sequence mode, control range defined by DIP n. 5
4	Modulating Control 0-10Vdc (DIP n. 2 OFF only)	Modulating Control 2-10Vdc (DIP n. 2 OFF only)
5	Sequence Control 0-5Vdc with DIP n. 4 OFF only Sequence Control 2-6Vdc with DIP n. 4 ON only (DIP n. 3 ON only)	Sequence Control 5-10Vdc with DIP n. 4 OFF only Sequence Control 6-10Vdc with DIP n. 4 ON only (DIP n. 3 ON only)
6	Voltage Input Signal (input between Y [+] and M [-])	Current Input Signal 4-20mA (input between Y [+] and M [-]). In this case DIP n. 4 must be set to ON.
7	Automatic Calibration: the actuator updates the stroke range every time an unexpected mechanical stop is detected for at least 10s	Manual Calibration: the actuator calibration is started moving the DIP from OFF to ON or vice versa. With DIP in ON in case of extra stroke or if an unexpected endpoint is detected, the actuator will never update the stroke

DIAGNOSTIC - ALARM FUNCTIONS

N°	LEDs behaviour	Error	Actuator use	Actuator	behaviour	Typical trouble shooting condition	Reset procedure
				Automatic calibration (DIP N. 7 OFF)	Manual calibration (DIP N. 7 ON)		
1	RED ON	Valve stroke less than 5mm	Calibration/first installation	The actuator pushes/pulls 2 times (unexpected stall) trying to remove the possible obstacle. After 2 tries an alarm is signalled and the actuator moves to initial position and does not respond to control signal. Stroke value is not updated because out of range	The actuator pushes/pulls 2 times against endpoint during calibration and the actuator moves to the initial position and then it does not respond to the control signal. The actuator keeps the previous stroke	Valve with a stroke length lower than 5mm	Remove power and power up again
2	RED quick blinking + GREEN ON	Stroke longer than 60mm	Calibration/first installation	The actuator exits the 60mm stroke range and it moves toward the new stroke limit signalling an anomaly. The actuator pushes/ pulls 2 times against the new stroke limit, then it goes back to the initial position still signalling the anomaly until it is not within 60mm. The actuator does not calibrate the stroke after 10s (wrong range)	The actuator exits the 60mm stroke range and it moves toward the new stroke limit signalling an anomaly. The actuator pushes/ pulls 2 times against the new stroke limit, then it goes back to the initial position still signalling the anomaly until it is not within 60mm. The actuator does not calibrate the stroke after 10s (wrong range)		Remove power and power up again
3	RED Quick Blinking	Unexpected stall within the calibrated stroke range	normal operation	The actuator tries 5 times against the new stall condition and then after 10s the actuator updates the new stroke length	The actuator tries 5 times against the new stall condition. At the end of the attempts the fault will be signalled. The actuator does not update the new stroke length, but after 60s makes other attempts to verify the stall condition	Valve stuck	Inverted control signal
4	RED Quick Blinking	Stroke longer than expected	Normal operation	The actuator moves toward the new stall condition with a lower speed; after 10s the actuator updates the new stroke value	The actuator moves toward the new stall condition with a lower speed; after 10s the actuator does not update the new stroke value	Stem connection loose or valve damaged	Inverted control signal
5	RED slow Blinking	Low Power Voltage	Normal operation	The actuator is still working but performance cannot be guaranteed	The actuator is still working but performance cannot be guaranteed	1. Wrong transformer size	Correct Voltage Powe
				353.311004		2. Unstable power	
6	RED slow Blinking	High Power Voltage	Normal operation	The actuator is still working but performance cannot be guaranteed	The actuator is still working but performance cannot be guaranteed	 Wrong transformer size Unstable power 	Correct Voltage Powe



N°	LED behaviour	Actuator status	
1	GREEN ON	N The actuator arrived at the extreme point of the stroke read	
2	GREEN BLINKING	The actuator arrived at the intermediate point of the stroke read	
3	RED GREEN BLINKING	The actuator is reading the stroke or it is going to initial position	
4	RED GREEN ON	Manual control ON, the actuators ignores the control signal. ATTENTION! The electronic board is electrically supplied	

DIMENSIONS [mm]





The performances stated in this sheet can be modified without any prior notice

